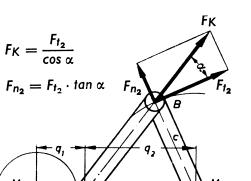
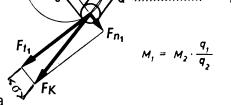
Übertragungsverhältnisse bei Gelenkgetrieben

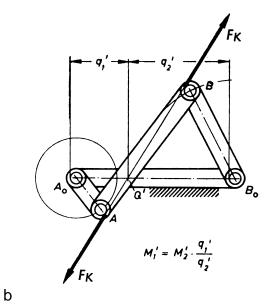
Tafel 6.1

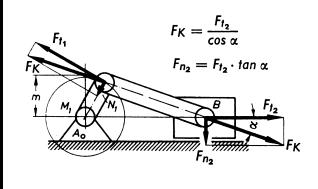
ohne Reibung



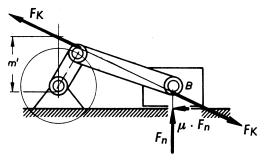


mit Reibung

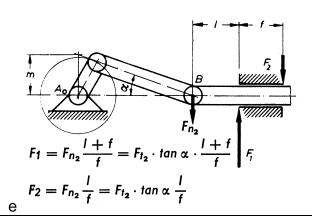


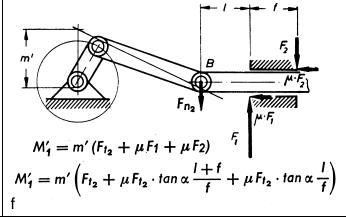


$$M_1 = m \cdot F_{t_2}$$



$$M'_1 = m' (F_{t_2} + \mu F_{n_2}) = m' (F_{t_2} + \mu F_{t_2} \cdot \tan \alpha)$$





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